

ON HIGHER DIMENSIONAL ORCHARD VISIBILITY PROBLEM

SHENGNING ZHANG

ABSTRACT. In this article, we study Pólya's orchard visibility problem in arbitrary dimension d : suppose at every integral point in \mathbb{R}^d , centered a small d -dimensional ball with radius r (which is considered as a tree at the integral point), given a d -dimensional ball centered at the origin O with radius R (which is considered as the orchard), it asks for the smallest r such that every ray starting from O will hit some tree in the orchard. We give both the upper and the lower bounds of the minimal value of r , say ρ in terms of R . Moreover, we prove that as $R \rightarrow \infty$, $\rho = \mathcal{O}(R^{-\frac{1}{d-1}})$.

1. INTRODUCTION

Let Λ be the set of lattice points $\mathbb{Z}^d \setminus O$ in \mathbb{R}^d , where O is the origin. Let $B(O, R)$ be the closed ball in \mathbb{R}^d centered at O with radius $R > 1$. Centering at every integral point $P \in B(O, R)$, is a small closed ball $B(P, r)$ with given small radius $r > 0$. The original Pólya's orchard visibility problem considers the case $d = 2$, when the disc $B(O, R)$ is thought as a round orchard and every $B(P, r)$ a tree at P , it asks for the smallest r , which we denote by ρ , so that one standing at the center O cannot see through the orchard, that is, for any ray l starting from O , $l \cap B(P, r) \neq \emptyset$ for some P .

In [1], it proved that

$$(1.1) \quad \frac{1}{\sqrt{R^2+1}} < \rho < \frac{1}{R}.$$

Indeed, in an earlier paper [2], Thomas Tracy Allen had proved that

$$(1.2) \quad \rho = \frac{1}{R}.$$

In this paper, we'd like to study the general Pólya's orchard problem in arbitrary dimension d and prove similar bounds as in (1.1). Our strategy follows [3], where, however, only deals with the 2 and 3 dimensional cases.

2. LOWER BOUNDS

Consider in \mathbb{R}^d the d -dimensional cuboid C with diagonal vertices O and $D := (1, 1, \dots, 1, [R] + 1)$, where $[R]$ is the floor function of R . Then

$$C \cap \mathbb{Z}^d = \{(x_1, \dots, x_d) \in \mathbb{Z}^d \mid x_i \in [0, 1], \forall i = 1, \dots, d-1; x_d \in [0, [R] + 1]\}.$$

Apparently, D is not in $B(O, R)$. The segment OD is of the length $\sqrt{(d-1) + R^2}$, and any $P \in C \cap \mathbb{Z}^d$ has the distance squared $dist(P, OD)^2$ to OD

$$(2.1) \quad \frac{(d-1 + ([R] + 1)^2)(x_1^2 + \dots + x_d^2) - (x_1 + \dots + x_{d-1} + ([R] + 1)x_d)^2}{d-1 + ([R] + 1)^2}$$

This lead us to our first result, which is a direct generalization to the first inequality of (1.1).

PROPOSITION 1. *notations as above*

$$(2.2) \quad \frac{\sqrt{d-1}}{\sqrt{d-1 + ([R] + 1)^2}} < \rho.$$

PROOF: Consider the formula (2.1), apparently that among all integral points in C other than O and D , $P_0 = \{0, \dots, 0, 1\}$ minimize the expression, when

$$dist(P_0, OD)^2 = \frac{d-1}{d-1 + ([R] + 1)^2}.$$

(see the figure below)

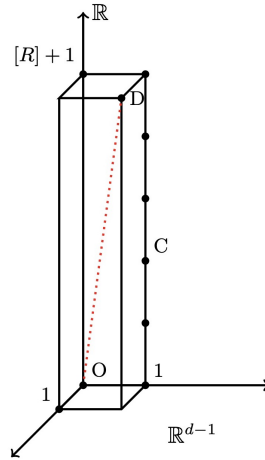


FIGURE 1

So if the tree radius r can block the orchard, it must bigger than $\frac{\sqrt{d-1}}{\sqrt{d-1 + ([R] + 1)^2}}$. This completes the proof. \square

The proposition tells us that ρ grows faster than the rate of R^{-1} as R goes to infinity, however, it is not the exact rate of growth of ρ , so we want a better lower bound of ρ in terms of R . Indeed, the proof of the proposition tells us that, to obtain such a lower bound, we have to consider a “finer” solid containing the ray than the coboid C above. To use such a solid in higher dimension, we have to use the volume formula of a lattice polyhedron in higher dimension developed by Macdonald in [4], which is the generalization of Pick’s Theorem used in [3, Theorem 2.2]. Now we summarize below.

Let $\mathbb{Z}^d \subset \mathbb{R}^d$ be the standard integral lattice, X a d -dimensional polyhedra in \mathbb{R}^d whose vertices are all in \mathbb{Z}^d . Let ∂X be the boundary of X , which can be viewed as a $(d-1)$ -simplicial complex. For any integer $n > 0$, write

$$L(n, X) = |X \cap \frac{1}{n}\mathbb{Z}^d|,$$

and

$$M(n, X) = L(n, X) - \frac{1}{2}L(n, \partial X),$$

then, we have the volume of X can be computed by:

PROPOSITION 2 (Macdonald’s Theorem). *The volume of the polyhedra $Vol(X)$ equals*

$$\frac{2}{(d-1)d!} \sum_{i=0}^{d-1} (-1)^i M(d-1-i, X) \binom{d-1}{i},$$

where $M(0, X) = 1$ if d is even, $M(0, X) = 0$ if d is odd.

Now we give us first theorem

THEOREM 1. *There is a constant $c > 0$ such that*

$$(2.3) \quad ([R] + 1)\rho^{d-1} > c.$$

Remark 1. The constant c is given by the volume of a polyhedra, which can be computed using Macdonald’s Theorem above. The key is to construct a proper polyhedra, which will be clear in the proof of the theorem.

LEMMA 1. *Point $Q \in \mathbb{Z}^d \cap B(O, R)$, if for any $P \in \mathbb{Z}^d \cap B(O, R)$, $OB \cap B(P, r) = \emptyset$, then the coordinates of Q are coprime, that is, if $Q = (a_1, \dots, a_d)$ then $\gcd(a_1, \dots, a_d) = 1$.*

The lemma comes from an easy observation. Suppose $\gcd(a_1, \dots, a_d) = d > 1$, then $P_1 = \frac{1}{d}(a_1, \dots, a_d) \in \mathbb{Z}^d \cap B(O, R)$ and obviously $OB \cap B(P_1, r) \neq \emptyset$. \square

LEMMA 2. *Let l be any ray starting from O , if point $P \in \mathbb{Z}^d \cap B(O, R)$, $P \notin l$ such that $\text{dist}(P, l)$ is minimal, then the coordinates of P are coprime.*

consider the point $Q = \frac{1}{m}P \in OP$. Find a point $Q' \in OA \subset \mathfrak{D}$ such that $QQ' \parallel AP$, then apparently that $dist(Q, \mathfrak{D}) < dist(P, \mathfrak{D})$. Contradiction! \square

PROOF OF THE THEOREM: Consider the point $D_1 := D$ given above, we view the segment OD as a vector from the origin O to D and denote it by \mathbf{l} . Among all integral points in $B(O, R)$, find P_2 in the first quadrant (that is, all the points are of nonnegative coordinates) be the one of minimal distance to \mathbf{l} . Write the minimal distance ε_1 . From the lemmas above, we know the coordinates of P_2 are coprime. View the segment OP_2 as a vector and denote it by \mathbf{v}_1 , and define vector $\mathbf{u}_1 := \mathbf{l} - \mathbf{v}_1$, define the two dimensional diamond D_2 be the parallelogram spanned by \mathbf{v}_1 and \mathbf{u}_1 . From the two lemmas above, D_2 does not contain any integral points of Λ other than the 4 vertices. Denote the 2-dimensional plane spanned by \mathbf{v}_1 and \mathbf{u}_1 by V_2 . Using our notion of diamond, D_2 is a 2-dimensional diamond with a diagonal \mathbf{l} .

Now among all integral points in $B(O, R) \setminus V_2$, find one P_3 in the first quadrant of the minimal distance to $V_2 \cap B(O, R)$. Write the minimal distance ε_2 . Consider the 2-dimensional diamond D_2 with diagonal \mathbf{l} and the point P_3 , by Definition 1, they together define a 3-dimensional diamond D_3 with diagonal \mathbf{l} . By Lemma 3, all the coordinates of P_3 are coprime, D_3 contains no integral points other than the 6 vertices. Denote the 3-dimensional vector space generated by vectors in D_3 by V_3 .

Keep this process, for all integer $i = 1, 2, \dots, d$, we obtain i -dimensional diamond D_i with diagonal \mathbf{l} , $V_i = span D_i$, integral points P_i in the first quadrant such that

- (a) $dist(P_i, V_{i-1} \cap V_i) = \varepsilon_{i-1}$ is minimal among all integral points in $B(O, R) \setminus V_{i-1}$;
- (b) D_i is the diamond constructed by D_{i-1} and P_i ;
- (c) D_i contains no integral points other than its vertices.

It is easy to see, from our construction, the volume of D_i is

$$(2.4) \quad Vol(D_i) = \frac{2^{i-1}}{i!} \varepsilon_1 \cdots \varepsilon_{i-1} ([R] + 1).$$

In particular, Write $\mathfrak{D} := D - d$, its volume is

$$(2.5) \quad Vol(\mathfrak{D}) = \frac{2^{d-1}}{d!} \varepsilon_1 \cdots \varepsilon_{d-1} ([R] + 1),$$

which can also be calculated by Macdonald's formula as in Proposition 2. On the other hand, By our construction of \mathfrak{D} , if the tree radius r is such that every ray starting from O and passing through one point in \mathfrak{D} will be blocked by some tree, then $r > \varepsilon_i$ for any i . So we have

$$(2.6) \quad \frac{2^{d-1}}{d!} r^{d-1} ([R] + 1) > Vol(\mathfrak{D}).$$

Writing

$$(2.7) \quad c = \frac{d! \text{Vol}(\mathfrak{D})}{2^{d-1}},$$

we complete the proof. \square

Remark 2. If $d = 2$, $\text{Vol}(\mathfrak{D}) = \text{Vol}(D_2) = 1$, then the Theorem tells that

$$(2.8) \quad ([R] + 1)\rho > 1,$$

which reproduces the result in [3, Proposition 2.4].

If $d = 3$, $\text{Vol}(\mathfrak{D}) = \text{Vol}(D_3) = \frac{2}{3} \times \frac{\sqrt{2}}{2} \times \frac{\sqrt{2}}{2} = \frac{1}{3}$, then the theorem tells that

$$(2.9) \quad ([R] + 1)\rho^2 > \frac{1}{2},$$

which is better than the result in [3, Proposition 4.4].

3. UPPER BOUNDS

In this section we give an upper bound of ρ in terms of R . The key ingredient is again Minkowski's theorem as [3, Theorem 4.1], which we summarize below.

PROPOSITION 3 (Minkowski's Theorem). *Let m be a positive integer and $F \subset \mathbb{R}^d$ a domain satisfying*

- (a) F is symmetric with respect to O ;
- (b) F is convex;
- (c) $\text{Vol}(F) > m2^d$.

Then F contains at least m pairs of points $\pm A_i \in \mathbb{Z}^d \setminus O$, $1 \leq i \leq m$, which are distinct from each other.

Now we state an upper bound of ρ . The idea is essentially same to [3, §4], where, however, only deals with the 3-dimensional case.

THEOREM 2. *There is a constant $C > 0$, such that*

$$(3.1) \quad R\rho^{d-1} < C.$$

PROOF: For any diameter AA' of the ball $B(O, R)$, let's consider the $d - 1$ -dimensional hyperellipsoid $E \subset \mathbb{R}^d$ as follow:

- (i) AA' is a long axis of E ;
- (ii) all other semi-axes of E are equal of length h .

Indeed, consider the function of d variables:

$$F(x_1, \dots, x_d) := \frac{x_1^2}{h^2} + \dots + \frac{x_{d-1}^2}{h^2} + \frac{x_d^2}{R^2},$$

then $F(x_1, \dots, x_d) = 1$ gives the hyperellipsoid when AA' is lying in the x_d -axis. Generally, if the line AA' has a unit directional vector \vec{u}_d , extend it to a orthonormal basis $\beta := \{\mathbf{u}_1, \dots, \mathbf{u}_{d-1}, \mathbf{u}_d\}$ of \mathbb{R}^d . Then there exists a unitary transformation $T : \mathbb{R}^d \rightarrow \mathbb{R}^d$ which sends β to the standard orthonormal basis $\{(1, 0, \dots, 0), \dots, (0, \dots, 0, 1)\}$ such that $T(\mathbf{u}_d) = (0, \dots, 0, 1)$. Then the $(d-1)$ -dimensional hyperellipsoid E has equation $F(T(x_1, \dots, x_d)) = 1$. See Figure 3.

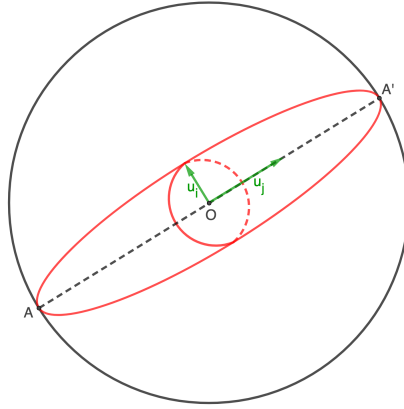


FIGURE 3

Now let $F \subset \mathbb{R}^d$ be the domain enclosed by E (including the points of E). Apparently, F satisfies the condition (a) and (b) of Minkowski's Theorem. Moreover, it is known that the volume of the hyperellipsoid is

$$(3.2) \quad \frac{\pi^{\frac{d}{2}}}{\Gamma(\frac{d}{2} + 1)} h^{d-1} R,$$

here Γ is the gamma function, so

$$(3.3) \quad \Gamma(\frac{d}{2} + 1) = \frac{d}{2} \Gamma(\frac{d}{2}) = \frac{d}{2} (\frac{d}{2} - 1) \cdots \gamma_0,$$

where $\gamma_0 = 1$ if d is even, $\gamma_0 = \frac{\pi}{2}$ if d is odd. By Minkowski's Theorem, if we choose h such that

$$(3.4) \quad \frac{\pi^{\frac{d}{2}}}{\Gamma(\frac{d}{2} + 1)} h^{d-1} R = 2^d + \varepsilon,$$

where ε is an arbitrary positive real number, then F contains an integral point other than O . This implies that, if we set $C = \frac{(2^d + \varepsilon) \Gamma(\frac{d}{2} + 1)}{\pi^{\frac{d}{2}}}$, and the tree radius $r = CR^{-\frac{1}{d-1}}$, then any ray segment OA starting from O will be blocked by some tree at the integral point contained in F we constructed as above. Since $\rho < r$, that we complete the proof. \square

Combining Theorem 1 and Theorem 2, we obtain the main result of this article:

THEOREM 3. *For d -dimensional orchard visibility problem, as the radius of orchard R goes to infinity,*

$$(3.5) \quad \rho = \mathcal{O}(R^{-\frac{1}{d-1}}).$$

4. SOME FURTHER THOUGHTS

We can still ask a lot of questions concerning the orchard visibility problem in arbitrary dimension. For example, for $d = 2$, it has been proved in [2] that $\rho = \frac{1}{R}$, or

$$(4.1) \quad \lim_{R \rightarrow \infty} \rho R = 1.$$

Inspired by our results, it is natural to ask if we can find a constant l for dimension d such that

$$(4.2) \quad \lim_{R \rightarrow \infty} \rho^{d-1} R = l.$$

However, our estimation in this article using polyhedra is apparently not precise and fine enough for such a conclusion. We will explore this problem in the future.

REFERENCES

- [1] Clyde P. Kruskal *The orchard visibility problem and some variants*, Journal of computer and system sciences, 74 (2008) 587–597.
- [2] Thomas Tracy Allen *Polya's Orchard Problem*, The American Mathematical Monthly, Vol. 93, No. 2 (1986) 98-104.
- [3] Alexandru Hening and Michael Kelly *On Polya's Orchard Problem*, Rose-Hulman Undergraduate Mathematics Journal: Vol. 7 : Iss. 2 , Article 9.
- [4] I. G. Macdonald *The volume of a lattice polyhedron*, Mathematical Proceedings of the Cambridge Philosophical Society, 59 (1963) 719-726.